

AUTOMOTIVE CURRENT TRANSDUCER OPEN LOOP TECHNOLOGY

HC16F 1000-S00; HC16F 1100-S00; HC16F 1200-S00; HC16F 1300-S00; HC16F 1400-S00; HC16F 1500-S00; HC16F 1600-S00

THD version (S00)



Introduction

The HC16F family is for the electronic measurement of DC, AC or pulsed currents in high power and high and low voltage automotive applications with galvanic separation between the primary circuit (high power) and the secondary circuit (electronic circuit).

The HC16F family gives you the choice of having different current measuring ranges in the same housing.

Features

- Ratiometric transducer
- Open Loop transducer using the Hall Effect
- High and Low voltage application
- Unipolar +5 V DC power supply
- Primary current measuring range ± 1000 A to ± 1600 A
- Maximum RMS primary admissible current: defined by busbar to have $T < +150$ °C
- Operating temperature range: -40 °C $< T < +125$ °C
- Output voltage: full ratio-metric (in sensitivity and offset)
- Compact design for PCB mounting.

Special features

- Housing with sleeve
- Dual air gap transducer
- Compact size.

Advantages

- Excellent accuracy
- Very good linearity
- Very low thermal offset drift
- Very low thermal sensitivity drift
- Galvanic separation
- High frequency bandwidth.

Automotive applications

- Electrical Power Steering
- Starter Generators
- Converters
- Motor drive application.

Principle of HC16F family

The open loop transducers uses a Hall effect integrated circuit. The magnetic flux density B , contributing to the rise of the Hall voltage, is generated by the primary current I_p to be measured. The current to be measured I_p is supplied by a current source i.e. battery or generator (Figure 1).

Within the linear region of the hysteresis cycle, B is proportional to:

$$B(I_p) = a \times I_p$$

The Hall voltage is thus expressed by:

$$U_{Hall} = (c_{Hall} / d) \times I_{Hall} \times a \times I_p$$

Except for I_p , all terms of this equation are constant. Therefore:

$$U_{Hall} = b \times I_p$$

a constant

b constant

c_{Hall} Hall coefficient

d thickness of the Hall plate

I_{Hall} current across the Hall plates

The measurement signal U_{Hall} amplified to supply the user output voltage or current.

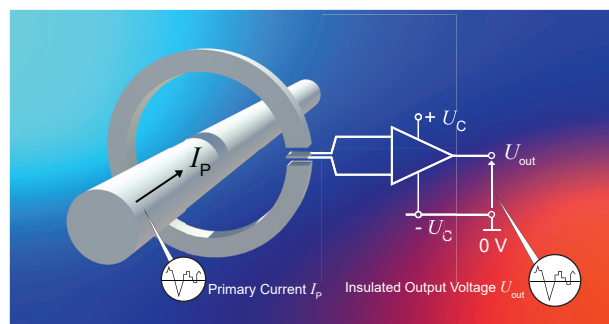
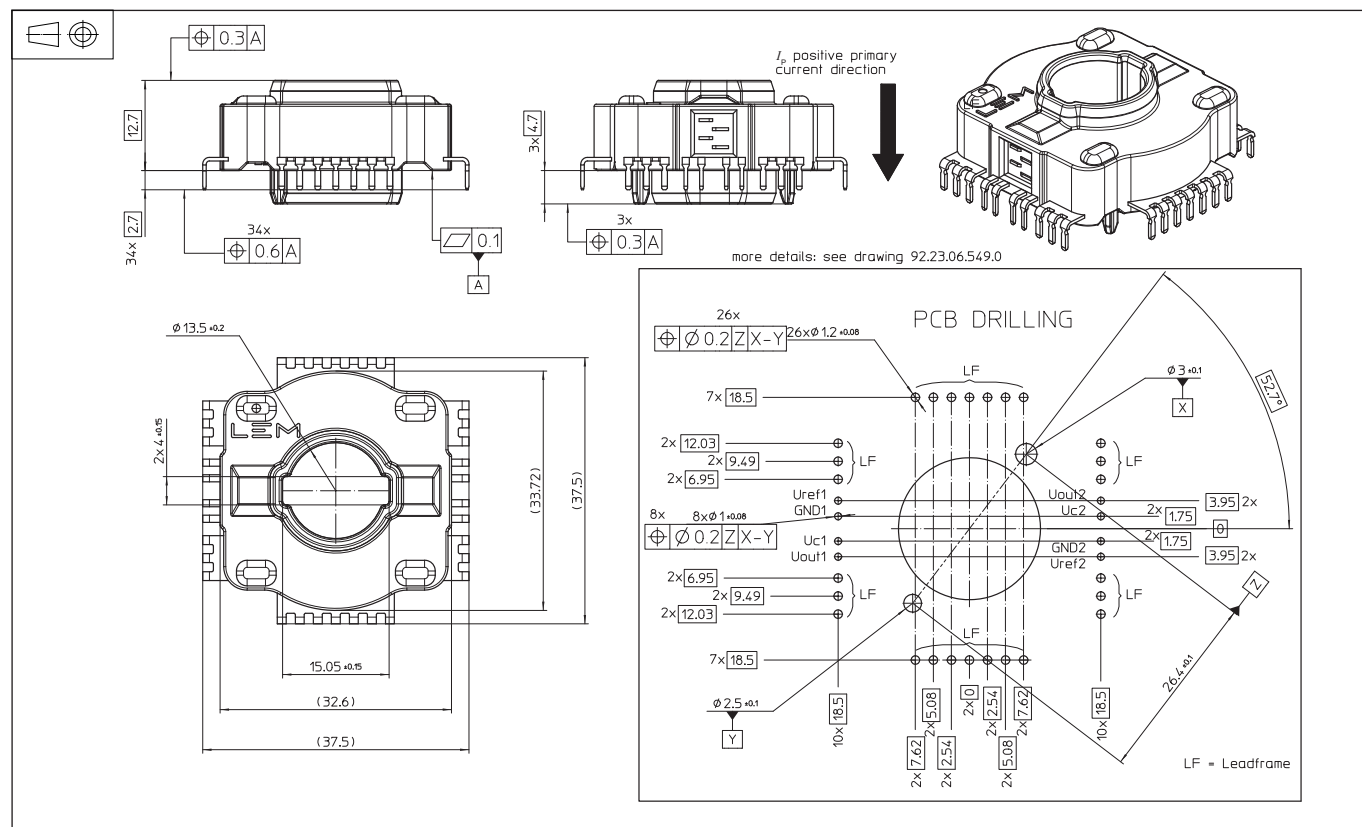


Fig. 1: Principle of the open loop transducer

Dimensions (in mm)

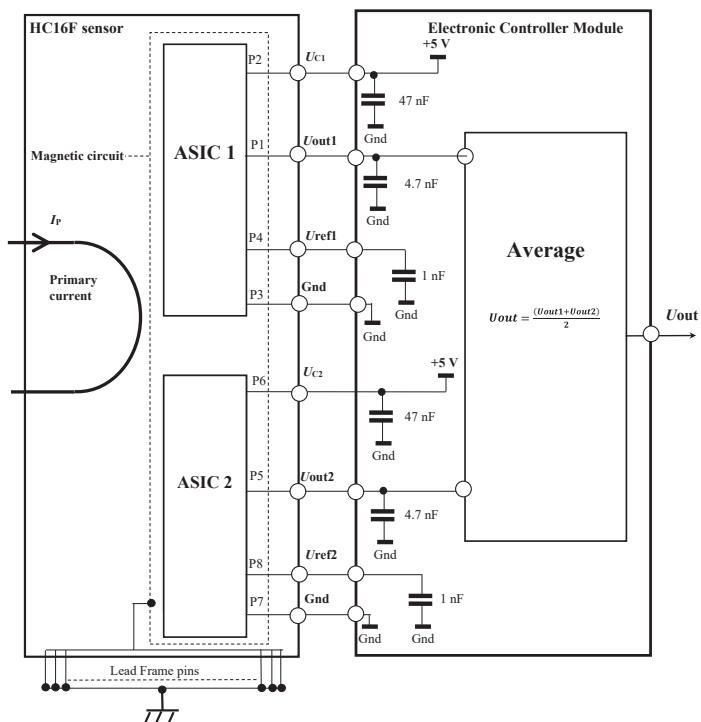
THD Version (S00)



Mechanical characteristics

- Plastic case >PPS-I-(GF + MD) 50<
- Magnetic core FeSi alloy
- Mass 29 g
- Lead frame Bronze tin plated

Electronic schematic



Remark

HC16F xxxx-S00

$U_{out} > U_O$ when I_p flows in the positive direction (see arrow on drawing).

- C_L Nominal value 4.7 nF $\pm 10\%$
- C_L is required for stabilization, EMC and ESD protection
- All the capacitors mentioned in the Electronic schematic should be mounted as close as possible to the ASIC pins
- The specifications are based on the average values of U_{out1} and U_{out2} (Computed by customer)
- For further information, please see "Applications" on page 9/12.

Absolute ratings (not operating)

Parameter	Symbol	Unit	Specification			Conditions
			Min	Typical	Max	
Maximum supply voltage	$U_{C\max}$	V	-0.5		8	Continuous, not operating
					6.5	Exceeding this voltage may temporarily reconfigure the circuit until U_C comes back to 5 V
Ambient storage temperature	$T_{A\text{st}}$	°C	-40		125	
Electrostatic discharge voltage	$U_{\text{ESD HBM}}$	kV			2	JESD 22-A 114-B Class 2
Maximum admissible vibration (random)	$\gamma_{\max}$	m·s ⁻²			107.3	ISO 16750-3 § 4.1.2.5 with Temperature
RMS voltage for AC insulation test, 50 Hz, 1 min	U_d	kV			3.6	IEC 60664-1, PD = 2, OV III altitude 400 m
Creepage distance	d_{Cp}	mm	11			
Clearance	d_{Cl}	mm	5			
Comparative tracking index	CTI			PLC3		
Maximum output current	$I_{\text{out 1 max}}, I_{\text{out 2 max}}$	mA	-10		10	Not operating
Maximum output voltage (Analog)	$U_{\text{out 1 max}}, U_{\text{out 2 max}}$	V	-0.5		$U_C + 0.5 \text{ V}$	Not operating
Maximum output short-circuit duration	$t_{\text{c max}}$	s			2	

Operating characteristics in nominal range (I_{PN})

Parameter	Symbol	Unit	Specification			Conditions
			Min	Typical	Max	
Electrical Data						
Supply voltage ¹⁾	U_C, U_{C1}, U_{C2}	V	4.85	5	5.15	
Ambient operating temperature	T_A	°C	-40		125	
Average of output voltages	$\overline{U}_{out}$	V	$\overline{U}_{out} = (U_C/5) \times (\overline{U}_O + \overline{S} \times I_P)$			
Current consumption	I_C	mA		28	35	@ $U_C = 5\text{ V}$
Load capacitance	C_L	nF	1	4.7	10	
Output internal resistance	R_{out1}, R_{out2}	Ω			10	
Performance Data ¹⁾						
Ratiometricity error	ε_r	%		±0.3		
Average of Sensitivity error	$\overline{\varepsilon}_S$	%		±0.5		@ $T_A = 25\text{ °C}$ (calibration error without T cycles), @ $U_C = 5\text{ V}$
Average of electrical offset voltage	$\overline{U}_{OE}$	mV		±3		@ $T_A = 25\text{ °C}$, @ $U_C = 5\text{ V}$
Average of magnetic offset voltage	$\overline{U}_{OM}$	mV		±2		@ $T_A = 25\text{ °C}$, after ± I_P , @ $U_C = 5\text{ V}$
Average temperature coefficient of $\overline{U}_{OE}$	$\overline{TCU}_{OEAV}$	mV/K	-0.08		0.08	@ $-40\text{ °C} < T < 125\text{ °C}$, $U_C = 5\text{ V}$
Average temperature coefficient of $\overline{S}$	$\overline{TCS}_{AV}$	%/K	-0.03		0.03	@ $-40\text{ °C} < T < 125\text{ °C}$, $U_C = 5\text{ V}$
Average linearity error	$\overline{\varepsilon}_{LAV}$	% I_{PM}		±0.5		Of full range I_{PM}
Delay time to 90 % of the final output value for I_{PN} step	t_{D90}	μs		2	4	@ 100 A/μs, I_{PM} Without C optional (see schematic1 on page9)
Frequency bandwidth ²⁾	BW	kHz	40			@ -3 dB, Without C optional
Peak-to-peak noise voltage	$U_{no\ pp}$	mV			15	DC to 1 MHz
Phase shift	$\Delta\Phi$	°	-3			DC to 1 kHz , Without C optional

Notes: ¹⁾ The output voltage U_{out} is fully ratiometric. The offset and sensitivity are dependent on the supply voltage U_C relative to the following formula:

$$I_P = \left(\frac{5}{U_C} \times \bar{U}_{\text{out}} - \bar{U}_O \right) \times \frac{1}{\bar{S}} \text{ with } S \text{ in (V/A)}$$

The specifications are based on the average values of $U_{\text{out 1}}$ and $U_{\text{out 2}}$ (completed by the customer).

²⁾ Primary current frequencies must be limited in order to avoid excessive heating of the busbar, magnetic core and the ASIC (see feature paragraph in page 1).

HC16F 1000-S00

Parameter	Symbol	Unit	Specification			Conditions
			Min	Typical	Max	
Electrical Data						
Primary current, measuring range	I_{PM}	A	−1000		1000	
Average of sensitivities	S_1, S_2	mV/A		2.00		@ $U_C = 5\text{ V}$
	$\overline{S}$					
Average of offset voltages	$\overline{U}_O$	V		2.5		@ $U_C = 5\text{ V}$

HC16F 1100-S00

Parameter	Symbol	Unit	Specification			Conditions
			Min	Typical	Max	
Electrical Data						
Primary current, measuring range	I_{PM}	A	−1100		1100	
Average of sensitivities	S_1, S_2	mV/A		1.82		@ $U_c = 5\text{ V}$
	$\overline{S}$					
Average of offset voltages	$\overline{U}_o$	V		2.5		@ $U_c = 5\text{ V}$

HC16F 1200-S00

Parameter	Symbol	Unit	Specification			Conditions
			Min	Typical	Max	
Electrical Data						
Primary current, measuring range	I_{PM}	A	-1200		1200	
Average of sensitivities	S_1, S_2	mV/A		1.67		@ $U_c = 5\text{ V}$
	$\overline{S}$					
Average of offset voltages	$\overline{U_o}$	V		2.5		@ $U_c = 5\text{ V}$

HC16F 1300-S00

Parameter	Symbol	Unit	Specification			Conditions
			Min	Typical	Max	
Electrical Data						
Primary current, measuring range	I_{PM}	A	−1300		1300	
Average of sensitivities	S_1, S_2	mV/A		1.54		@ $U_C = 5\text{ V}$
	$\overline{S}$					
Average of offset voltages	$\overline{U}_o$	V		2.5		@ $U_C = 5\text{ V}$

HC16F 1400-S00

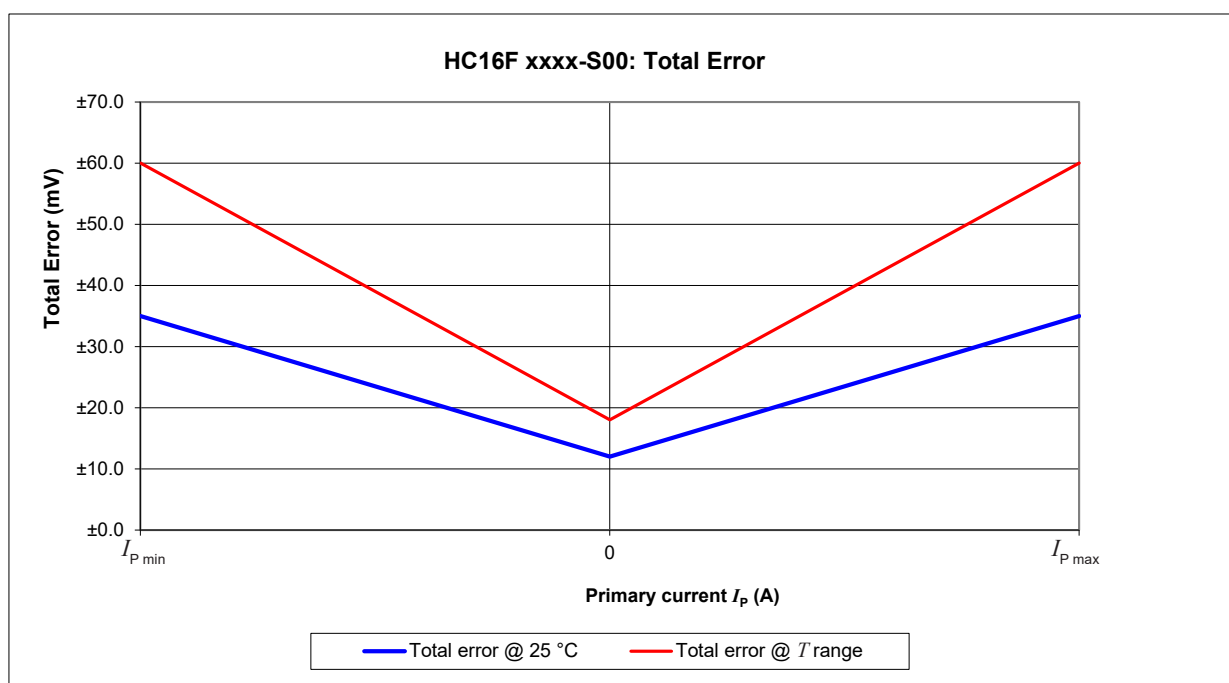
Parameter	Symbol	Unit	Specification			Conditions
			Min	Typical	Max	
Electrical Data						
Primary current, measuring range	I_{PM}	A	−1400		1400	
Average of sensitivities	S_1, S_2	mV/A		1.43		@ $U_c = 5\text{ V}$
	$\bar{S}$					
Average of offset voltages	$\bar{U}_O$	V		2.5		@ $U_c = 5\text{ V}$

HC16F 1500-S00

Parameter	Symbol	Unit	Specification			Conditions
			Min	Typical	Max	
Electrical Data						
Primary current, measuring range	I_{PM}	A	−1500		1500	
Average of sensitivities	S_1, S_2	mV/A		1.33		@ $U_c = 5\text{ V}$
	$\overline{S}$					
Average of offset voltages	$\overline{U_o}$	V		2.5		@ $U_c = 5\text{ V}$

Parameter	Symbol	Unit	Specification			Conditions
			Min	Typical	Max	
Electrical Data						
Primary current, measuring range	I_{PM}	A	−1600		1600	
Average of sensitivities	S_1, S_2	mV/A		1.25		@ $U_c = 5\text{ V}$
	$\overline{S}$					
Average of offset voltages	$\overline{U_o}$	V		2.5		@ $U_c = 5\text{ V}$

Total error of U_{out} (Average value)

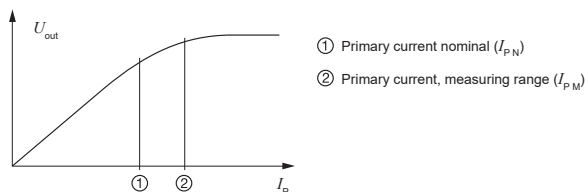


Primary current I_P	Total error @ 25 °C		Total error @ T range	
	in A	in mV	in mV	in %
$I_{P\ min}$		±35.0 (*)	±60.0	±3.00
0		±12.0	±18.0	±0.90
$I_{P\ max}$		±35.0 (*)	±60.0	±3.00

(*): ±45 mV after High T °C High Humidity (1000 h 85 °C / 85 % RH).

PERFORMANCES PARAMETERS DEFINITIONS

Primary current definition:



Definition of typical, minimum and maximum values:

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as values shown in "typical" graphs. On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval. Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %. For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and $+3$ sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between $-\text{sigma}$ and $+\text{sigma}$ for a normal distribution. Typical, minimum and maximum values are determined during the initial characterization of a product.

Output noise voltage:

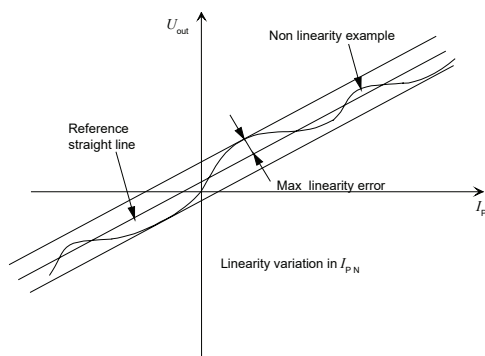
The output voltage noise is the result of the noise floor of the Hall elements and the linear amplifier.

Magnetic offset:

The magnetic offset is the consequence of an any current on the primary side. It's defined after a stated excursion of primary current.

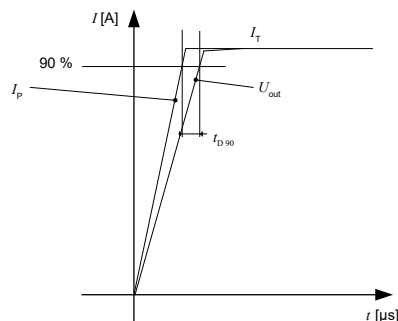
Linearity:

The maximum positive or negative discrepancy with a reference straight line $U_{out} = f(I_p)$.
Unit: linearity (%) expressed with full scale of I_{pN} .



Delay time t_{D90} :

The time between the primary current signal (I_{pN}) and the output signal reach at 90 % of its final value.



Sensitivity:

The transducer's sensitivity S is the slope of the straight line $\bar{U}_{out} = f(I_p)$, it must establish the relation:

$$\bar{U}_{out}(I_p) = U_C / 5 (\bar{S} \times I_p + \bar{U}_O)$$

Offset with temperature:

The error of the offset in the operating temperature is the variation of the offset in the temperature considered with the initial offset at 25 °C.

The offset variation I_{OT} is a maximum variation the offset in the temperature range:

$$I_{OT} = I_{OE \max} - I_{OE \min}$$

The offset drift $\overline{TCI}_{OE \Delta V}$ is the I_{OT} value divided by the temperature range.

Sensitivity with temperature:

The error of the sensitivity in the operating temperature is the relative variation of sensitivity with the temperature considered with the initial offset at 25 °C.

The sensitivity variation S_T is the maximum variation (in ppm or %) of the sensitivity in the temperature range:
 $S_T = (\text{Sensitivity max} - \text{Sensitivity min}) / \text{Sensitivity at } 25^\circ\text{C}$.

The sensitivity drift $\overline{TCS}_{\Delta V}$ is the S_T value divided by the temperature range. Deeper and detailed info available is our LEM technical sales offices (www.lem.com).

Offset voltage @ $I_p = 0$ A:

The offset voltage is the output voltage when the primary current is zero. The ideal value of U_O is $U_C / 2$. So, the difference of $U_O - U_C / 2$ is called the total offset voltage error. This offset error can be attributed to the electrical offset (due to the resolution of the ASIC quiescent voltage trimming), the magnetic offset, the thermal drift and the thermal hysteresis. Deeper and detailed info available is our LEM technical sales offices (www.lem.com).

Environmental test specifications:

Refer to LEM GROUP test plan laboratory CO.11.11.515.0 with "Tracking_Test Plan_Auto" sheet.

Environmental test specifications:

Refer to LEM GROUP test plan laboratory CO.11.11.515.0 with "Tracking_Test Plan_Auto" sheet.

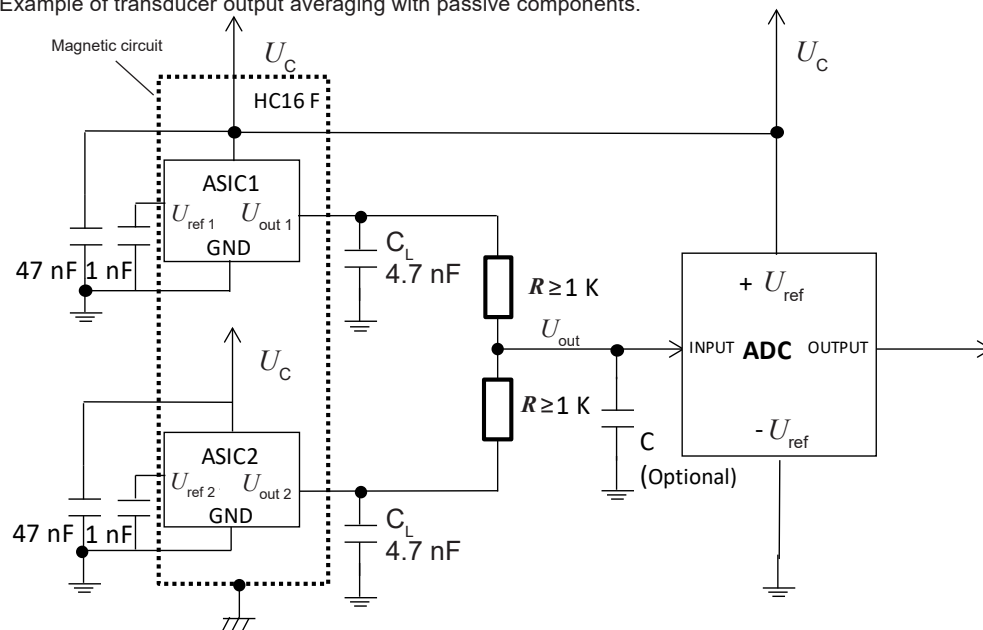
Name	Standard	Conditions
ELECTRICAL TESTS		
Phase shift, frequency bandwidth	LEM Procedure	100 Hz to 100 kHz, 100 A peak
Noise measurement	LEM Procedure	Sweep from DC to 1 MHz
Delay time di/dt	LEM Procedure	100 A/ μ s $I_{pulse} = I_{P_{max}}$
du/dt	LEM Procedure	5 ; 10 ; 20 kV/ μ s $U = 1000$ V
RMS voltage for AC insulation test	IEC 60664 part 1	3.6 kV AC / 1 min / 50 Hz ($I < 0.1$ mA)
Insulation resistance test	ISO 16750-2 (2010)	500 V DC time = 60 s $R_{INS} \geq 500$ M Ω Min
ENVIRONMENTAL TESTS		
High T° C High Humidity Electrical connection	JESD 22-A 101 (03/2009)	1000 h 85 $^{\circ}$ C / 85 % RH $U_C = 5$ V DC, $I_P = 0$ A
Thermal Cycle Test (Simplified profile)	IEC 60068-2-14 Test Nb (01/2009)	$T_{min} -40^{\circ}$ C , $T_{max} = +125^{\circ}$ C 1 cycle = 480 min, 30 cycles
Thermal Shock	ISO 16750-4 § 5.3.2 (04/2010)	1000 cycles 30 min "-40 $^{\circ}$ C" // 30 min "+85 $^{\circ}$ C" U_C not connected $I_P = 0$ A
High T° C Storage	IEC 60068-2-2 Bd (07/2007)	125 $^{\circ}$ C for 1000 h U_C not connected $I_P = 0$ A
Low T° C Storage	IEC 60068-2-1 Ad (03/2007)	-40 $^{\circ}$ C for 240 h U_C not connected $I_P = 0$ A
Mechanical Shock	ISO 16750-3 § 4.2.2 (12/2012)	500 ms/s ² , 6 ms Half Sine @ 25 $^{\circ}$ C 10 shocks of each direction U_C not connected $I_P = 0$ A
Random Vibration in T° C profile 1	ISO 16750-3 § 4.1.2.5 IEC 60068-2-27 (02/2008)	Vibration profile E- For Unsprung masses (chassis) in T° C : 8 h/axis, 107.3 m/s ² RMS
Random Vibration in T° C profile 2	ISO 16750-3 § 4.1.2.2.3 IEC 60068-2-27 (02/2008)	Vibration profile: Passenger car, Gearbox in T° C : 22 h/axis, 96.6 m/s ² RMS
EMC TESTS		
Radiated Emission Absorber Lined Shielded Enclosure (ALSE)	CISPR 25 (2008) Table 9 - Class 5	$f = 150$ kHz to 2.5 GHz Criteria A acceptance @ 5 % of 2 V
Radiated Immunity Bulk Current Injection (BCI)	GWM 3097 § 3.4.1 (2015)	Level : GMW 3097 (2015) § 3.4.1 Table 13 - Level 1 (100 mA) (ISO 11452 - 4 (2011) Annex E Table E 1 Level 2) $f = 1$ MHz to 400 MHz , Criteria A acceptance @ 5 % of 2 V
Radiated Immunity Anechoic chamber	GWM 3097 § 3.4.2 (2015)	Level : GMW 3097 (2015) § 3.4.2 Table 14 - Level 2 (100 V/m) $f = 400$ MHz to 1 GHz; Level = 100 V/m (CW, AM 80 %) $f = 0.8$ GHz to 2 GHz; Level = 70 V/m (CW, PM PRR = 217 Hz PD = 0.57 ms); $f = 1$ GHz to 2 GHz; Level = 70 V/m (CW) Criteria A acceptance @ 5 % of 2 V
ESD Test	GWM 3097 § 3.6.3 (2015)	Level : GMW 3097 (2015) § 3.6.3.3 Table 28 Contact discharges: ± 4 , ± 6 kV; Air discharges: ± 8 kV $U_C =$ NO power supply ($\equiv$ unconnected), Criteria B
Free Fall	ISO 16750-3 § 4.3 (12/2012)	Height = 1 m Concrete floor 3 axis, 2 directions by axis, 1 sample by axis

Applications:

Customers have to compute the Average value of U_{out1} and U_{out2} . This could be done by a resistive bridge as showing in schematic 1 or any other means defined by customers (for example with a micro-controller as showing in schematic 2).

Schematic 1:

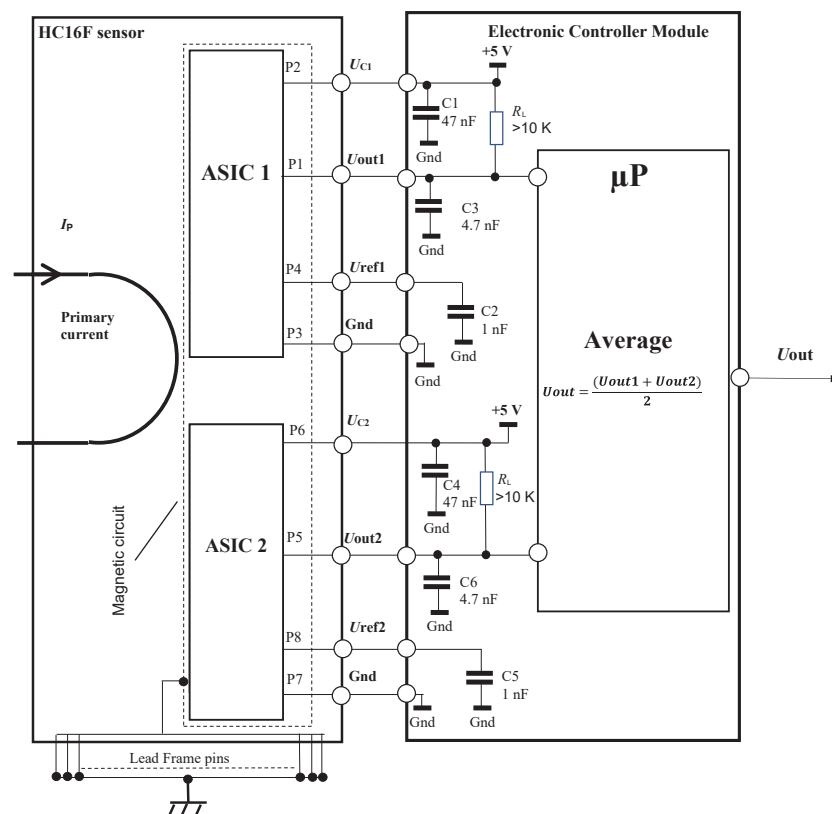
Example of transducer output averaging with passive components.



Resistance: $R \geq 1 \text{ K}$, 1 %, 100 ppm/°C, 100 mW, 75 V, -40 ... 155 °C, 0603 (or better)

Schematic 2:

Example of transducer averaging with a micro-controller.

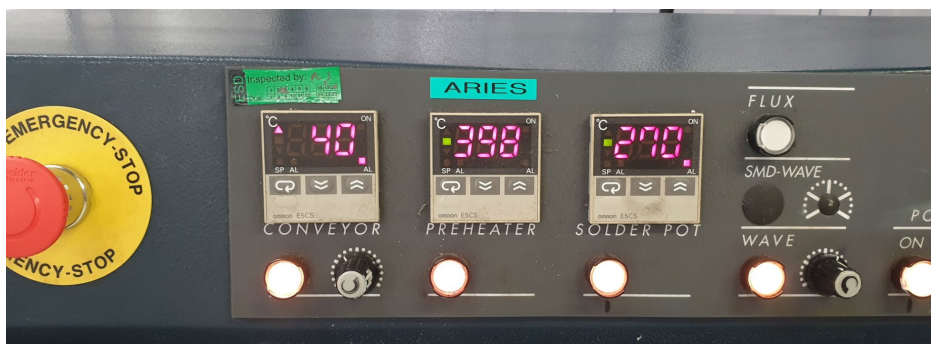


Soldering recommendation:

LEM recommends to use the following equipment parameters for the soldering of HC16F xxxx-S00 family. Nevertheless, customer is remaining responsible for final solder joints validation as it's deeply depending on many parameters not controlled by LEM.

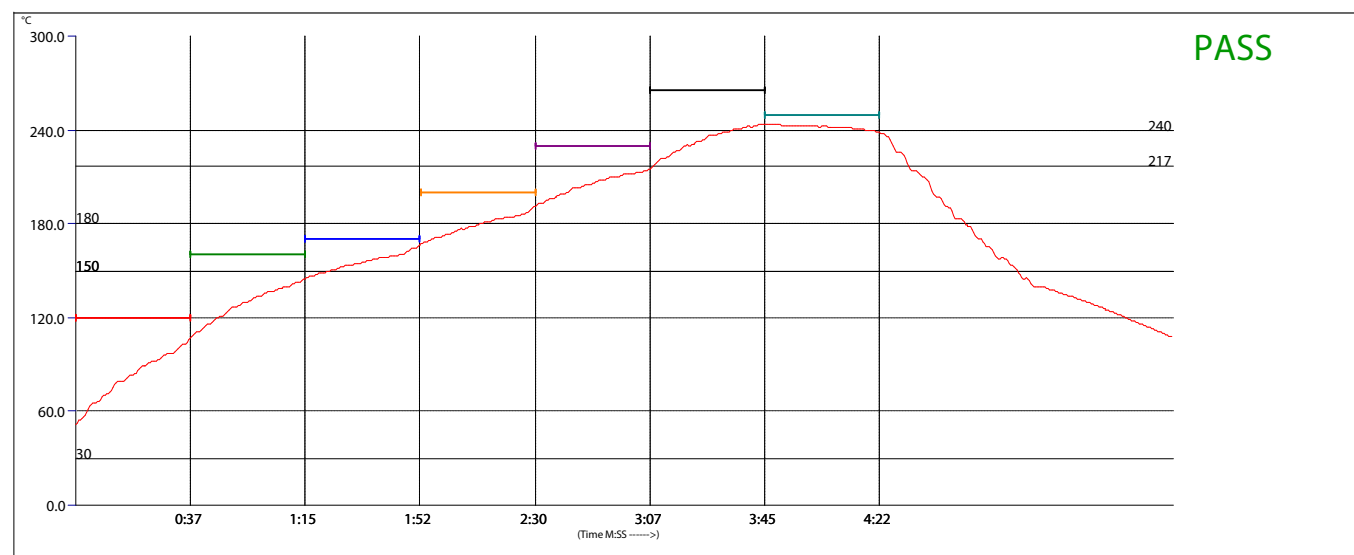
1. Wave soldering Through Holes Device (THD) for HC16F xxxx-S00:

- Machine ARIES
- SN 100C lead free solder
- Flux FS 110 (of Sodiflux)
- LEM recommended - PCB layout : according to gerber file of PCB 2569-00
- Temperature profile as below:
Conveyor speed = 40 cm/min; Preheater = 400 °C; Solder pot = 270 °C.



2. Reflow soldering THD (by Pin in Paste for HC16F xxx-S00) :

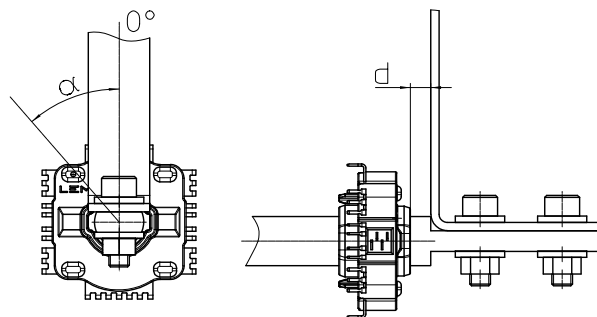
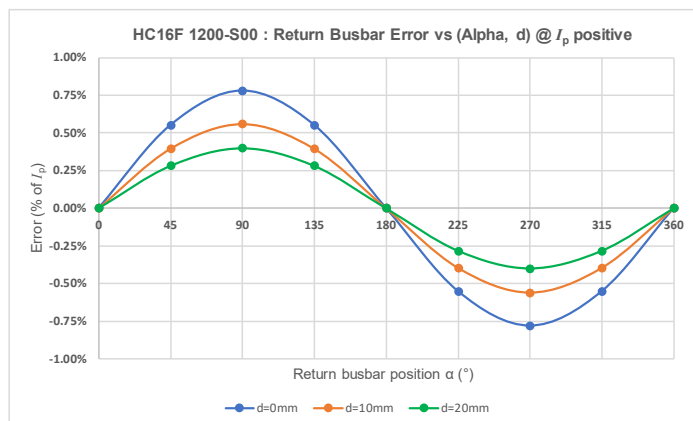
- Machine HELLER 1707 MK3
- Solder Paste Ecorel Free 305-16T4
- Solder paste thickness 200 µm
- LEM recommended - PCB layout : according to gerber file of PCB 2569-00 for THD version
- Temperature profile as below:



Process parameters				Consign of zones (Machine Heller 1707 MK III)							
Type of alloy (Solder paste)	INVENTEC ECOREL FREE 305-16 T4				Z1	Z2	Z3	Z4	Z5	Z6	Z7
	Min	Max	Units	Upper Heat (°C)	120	160	170	200	230	265	250
Preheat time (150 °C -180 °C)	30	130	seconds	Lower heat (°C)	120	160	170	200	230	265	250
Liquidus time (r °C > 217 °C)	45	100	seconds								
Pick T °C	230	250	°C	Speed (cm/min)	40						

Recommendation on Return busbar's position

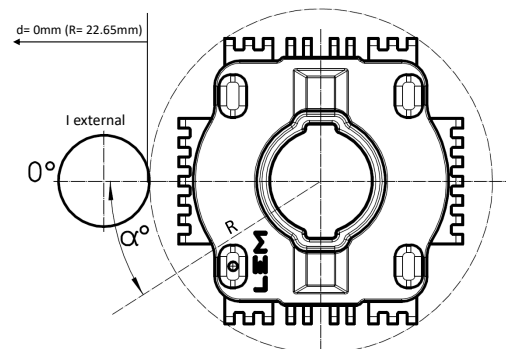
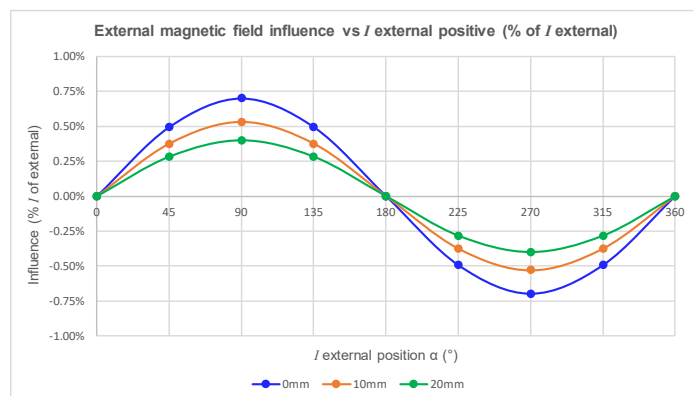
Busbar return influence @ I_p : the positive current direction as defined on page 2.
The best position $\alpha = 0^\circ$ and 180° .



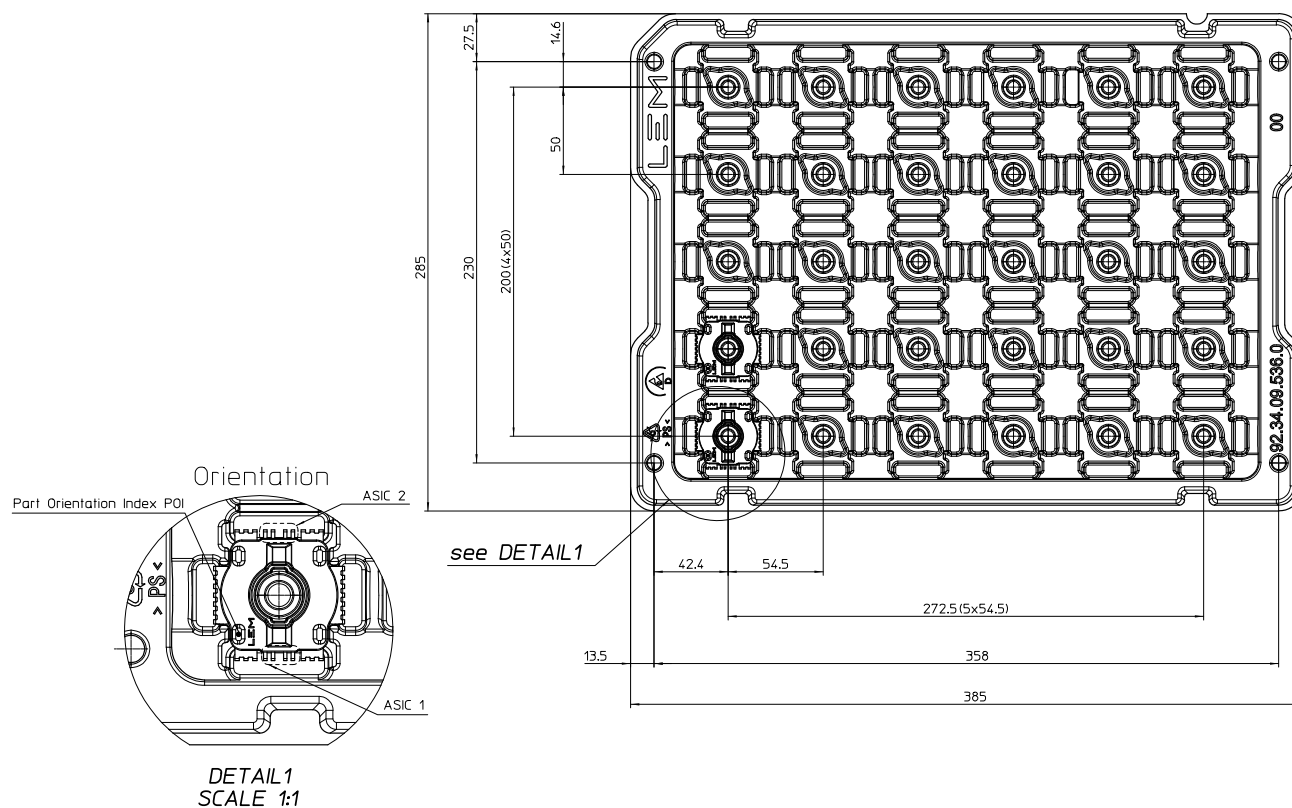
The return busbar error is the relative error generated by the return busbar in comparison with the straight busbar.

Recommendation – External magnetic sources position

External magnetic field influence @ I_{external} : the positive current direction as defined on page 2.
The best position $\alpha = 0^\circ$ and 180° .



Tray packaging of transducer HC16F



Notes : For the dimensions of the transducers HC16F, please see page 2/12
Advice insertion force of 4N minimum for an automatic placement on the PCBA.

IMPORTANT NOTICE

The information in this document is considered accurate and reliable. However, LEM International SA and any company directly or indirectly controlled by LEM Holding SA ("LEM") do not provide any guarantee or warranty, expressed or implied, regarding the accuracy or completeness of this information and are not liable for any consequences resulting from its use. LEM shall not be responsible for any indirect, incidental, punitive, special, or consequential damages (including, but not limited to, lost profits, lost savings, business interruption, costs related to the removal or replacement of products, or rework charges) regardless of whether such damages arise from tort (including negligence), warranty, breach of contract, or any other legal theory.

LEM reserves the right to update the information in this document, including specifications and product descriptions, at any time without prior notice. Information in this document replaces any previous versions of this document. No license to any intellectual property is granted by LEM through this document, either explicitly or implicitly. Any Information and product described herein is subject to export control regulations.

LEM products may possess either unidentified or documented vulnerabilities. It is the sole responsibility of the purchaser to design and operate their applications and products in a manner that mitigates the impact of these vulnerabilities. LEM disclaims any liability for such vulnerabilities. Customers must select products with security features that best comply with applicable rules, regulations, and standards for their intended use. The purchaser is responsible for making final design decisions regarding its products and for ensuring compliance with all legal, regulatory, and security-related requirements, irrespective of any information or support provided by LEM.

LEM products are not intended, authorized, or warranted for use in life support, life-critical, or safety-critical systems or equipment, nor in applications where failure or malfunction of an LEM product could result in personal injury, death, or significant property or environmental damage. LEM and its suppliers do not assume liability for the inclusion and/or use of LEM products in such equipment or applications; thus, this inclusion and/or use is at the purchaser's own and sole risk. Unless explicitly stated that a specific LEM product is automotive qualified, it should not be used in automotive applications. LEM does not accept liability for the inclusion and/or use of non-automotive qualified products in automotive equipment or applications.

Applications that are described herein are for illustrative purposes only. LEM makes no representation or warranty that LEM products will be suitable for a particular purpose, a specified use or application. The purchaser is solely responsible for the design and operation of its applications and devices using LEM products, and LEM accepts no liability for any assistance with any application or purchaser product design. It is purchaser's sole responsibility to determine whether the LEM product is suitable and fit for the purchaser's applications and products planned, as well as for the planned application and use of purchaser's third-party customer(s).

Stressing and using LEM products at or above limiting values will cause permanent damage to the LEM product and potentially to any device embedding or operating with LEM product. Limiting values are stress ratings only and operation of the LEM product at or above conditions and limits given in this document is not warranted. Continuous or repeated exposure to limiting values will permanently and irreversibly affect the quality and reliability of the LEM product.

LEM products are sold subject to the general terms and conditions of commercial sale, as published at www.lem.com unless otherwise agreed in a specific written agreement. LEM hereby expressly rejects the purchaser's general terms and conditions for purchasing LEM products by purchaser. Any terms and conditions contained in any document issued by the purchaser either before or after issuance of any document by LEM containing or referring to the general terms and conditions of sale are explicitly rejected and disregarded by LEM, and the document issued by the purchaser is wholly inapplicable to any sale or licensing made by LEM and is not binding in any way on LEM.

© 2025 LEM INTERNATIONAL SA – All rights reserved